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Game Technology **Winter Semester 2016/2017**

Solution 6

General Information

- The exercises may be solved by teams of up to three people.
- The solutions have to be uploaded to the Git repositories assigned to the individual teams.
- **The submission date (for practical and theoretical tasks) is noted on top of each exercise sheet.**
- If you have questions about the exercises write a mail to game-technology@kom.tu-darmstadt.de or use the forum at <https://www.fachschaft.informatik.tu-darmstadt.de/forum/viewforum.php?f=557>

P6. Practical Tasks: Bumps and Animations (5 Points)

Get the source code of this exercise from <https://github.com/TUDGameTechnology/Exercise6.git>. For a reference to how the exercise's solution should look like, please look at the video on the course homepage.

Please remember to push into a branch called "exercise6".

You can find the solution source code in the exercise at <https://github.com/TUDGameTechnology/Solution6.git>.

P6.1 Normal Maps (2 points)

On the right side of the exercise, you can find a box. For this box, a tangent-space normal map is provided.

- a) Implement the creation of the tangent space basis (see comments in Exercise.cpp). Use the vertices of the mesh and their UV coordinates for this task. Please finish Task T6.1 first, as you will be deriving the necessary formula there.
- b) Implement the missing part of the pixel shader (see comments in shader.frag).

P6.2 Vertex Animation (3 points)

On the left side of the exercise, you can find a pie-chart with a peculiar shape... The object is provided as a mesh with the center of the shape at the model's origin. Animate the model in the vertex shader so that the opening at the right side appears to open and close rhythmically.

Hints:

- You can treat the problem as 2D and ignore the z-coordinate of the model
- Think about how one vertex (e.g. at the "mouth") has to move and try to find functions which realize this movement, then apply them to all vertices.

T6. Theoretical Tasks: Graphics Mix (5 Points)

T6.1 Tangent Space Basis (1 point)

As a preparation for P6.1 a), please derive the formulae for calculating T and B, the tangent and binormal vectors, from the differences in the vertex positions and UV coordinates of the triangle:

$$\begin{aligned}\Delta \text{Pos}_1 &= \Delta u_1 * T + \Delta v_1 * B \\ \Delta \text{Pos}_2 &= \Delta u_2 * T + \Delta v_2 * B\end{aligned}$$

Hint: Treat the two equations as a system of linear equations and solve it.

As hinted at in the exercise, we write out the equations and solve the resulting system of equations. The easiest way to carry this out is by re-writing this as using a matrix and inverting it to solve the system:

$$\begin{aligned}\begin{pmatrix} \Delta x_1 \\ \Delta x_2 \end{pmatrix} &= \begin{pmatrix} \Delta u_1 & \Delta v_1 \\ \Delta u_2 & \Delta v_2 \end{pmatrix} \begin{pmatrix} T \\ B \end{pmatrix} \\ \det \begin{pmatrix} \Delta u_1 & \Delta v_1 \\ \Delta u_2 & \Delta v_2 \end{pmatrix} &= \Delta u_1 \Delta v_2 - \Delta u_2 \Delta v_1 = d \\ \begin{pmatrix} \Delta u_1 & \Delta v_1 \\ \Delta u_2 & \Delta v_2 \end{pmatrix}^{-1} &= \frac{1}{d} \begin{pmatrix} \Delta v_2 & -\Delta v_1 \\ -\Delta u_2 & \Delta u_1 \end{pmatrix}\end{aligned}$$

$$\frac{1}{d} \begin{pmatrix} \Delta v_2 & -\Delta v_1 \\ -\Delta u_2 & \Delta u_1 \end{pmatrix} \begin{pmatrix} \Delta x_1 \\ \Delta x_2 \end{pmatrix} = \frac{1}{d} \begin{pmatrix} \Delta v_2 \Delta x_1 - \Delta v_1 \Delta x_2 \\ -\Delta u_2 \Delta x_1 + \Delta u_1 \Delta x_2 \end{pmatrix}$$

$$T = \frac{1}{d} (\Delta v_2 \Delta x_1 - \Delta v_1 \Delta x_2)$$

$$B = \frac{1}{d} (-\Delta u_2 \Delta x_1 + \Delta u_1 \Delta x_2)$$

We see that we can re-use the determinant in the calculations.

T6.2 Relief Parallax Mapping (1 point)

In the lecture, we looked at the techniques Parallax Mapping, Steep Parallax Mapping and Parallax Occlusion Mapping. We skipped one technique called *Relief Parallax Mapping*, developed by Manuel M. Oliveira. Research this technique and describe how it works in comparison to the other parallax mapping techniques we introduced.

Relief Parallax Mapping improves the quality of the result by adding a binary search step, in which the correct intersection between the view ray and the surface as defined by the heightmap is searched for.

You can read an overview of the algorithm for example in this report:

<http://members.gamedev.net/fortia/RTMReport.final.pdf>

T6.3 Particles (1 point)

Particle systems consist of lots and lots of semi-transparent billboards. Depth buffer-based 3D rendering does not handle transparency well. What problem must be avoided and can that be done efficiently? When all is set and done, what is likely to be the biggest performance burden when rendering particles?

The problem we need to avoid is drawing the alpha-blended semitransparent particles in the wrong order. To counteract this, particles have to be sorted by distance.

If particles are aligned to always show towards the camera, this can be done somewhat efficiently, since they cannot intersect in this case.

The biggest performance problem is typically overdraw because the graphics chip renders lots of semi-transparent pixels on top of each other. Overdraw is the problem that the same pixel in the output image is drawn several times. When a z-buffer is used, this problem is usually lessened, since pixels that do not pass the z-buffer-test are rejected and not drawn at all. However, for semi-transparent geometry, this is not possible.

T6.4 Deferred Shading (1 point)

Game engines using deferred shading usually add a forward shading pass for materials that require blending. Explain why this is necessary.

In deferred shading, we render the whole scene into our G-Buffers and then do shading on them. Since G-Buffers are just textures/render targets that are 2D, we face a similar problem as the one we have with blending and z-buffering: Only the information of one particle will be written into the G-Buffer.

However, for blending, we need to combine the shaded color of the background with the color of the object in front, possibly several times if several objects overlap each other. Since we do not have the shading information yet when rendering the scene, the materials using blending cannot be drawn correctly.

A common solution is to first render the opaque materials first using deferred shading and then render the remaining materials onto the image rendered so far.

You can find an overview over possible solutions to this problem on this website: <http://www.john-chapman.net/content.php?id=13>

T6.5 Skeletal Animations (1 point)

Will the problem we referred to as "Achselhölle"/"candy wrapper problem" in the lecture also occur if the most number of bones that influence any vertex in the mesh is 1, i.e. if every vertex is only bound to one bone? Explain your answer.

Yes, it will also occur in this configuration.

The vertices will still be connected with edges. If a loop of vertices v_1 is bound to bone b_1 only and a second loop v_2 is connected to it and bound to bone b_2 only, if one or both bones are rotated, the effect will occur.

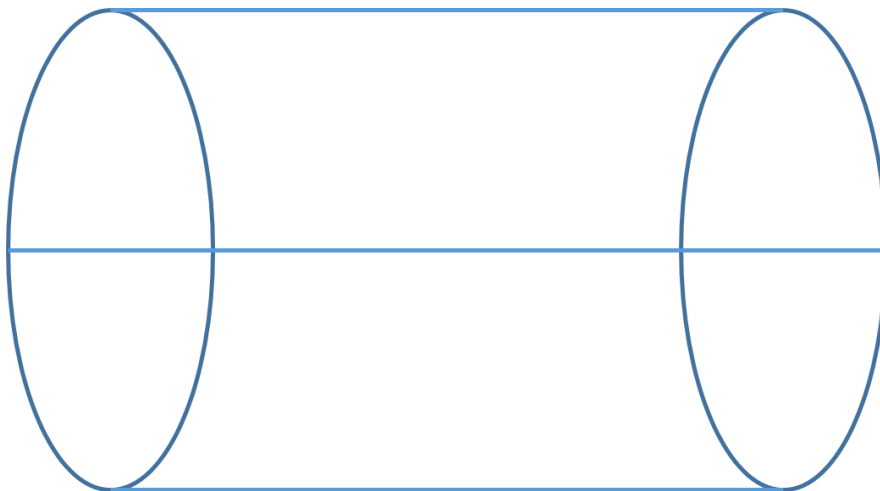


Figure 1: Two loops of vertices connected by edges.

